

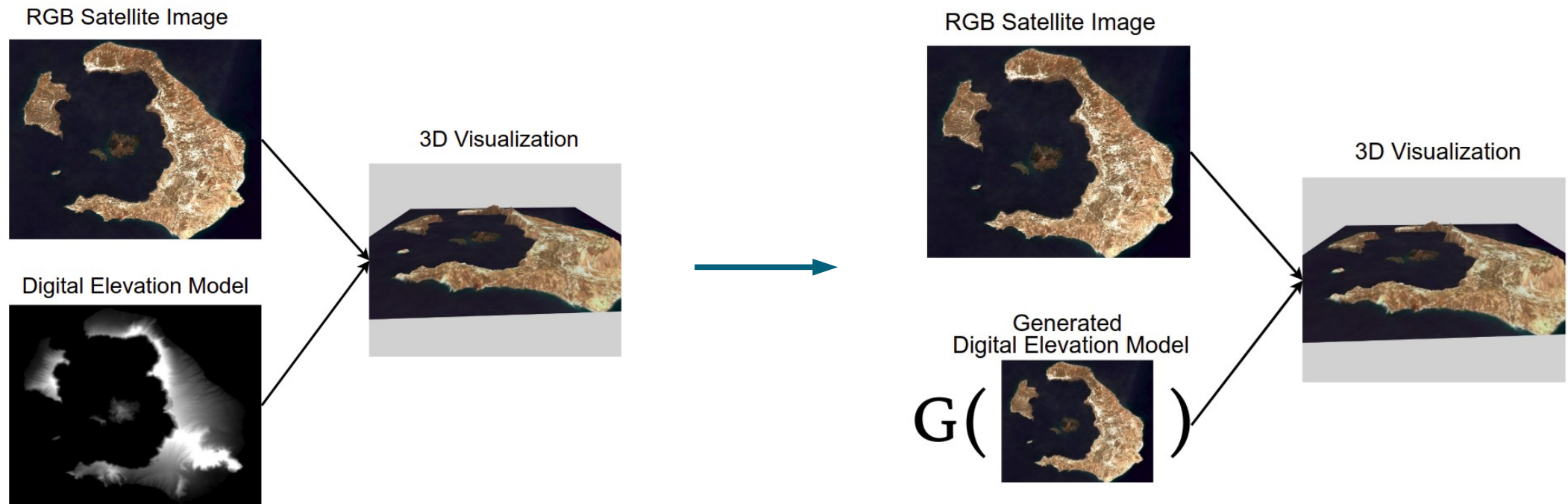
Predicting Surface Elevation from a single RGB satellite image

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Eleni Charou



DEMOKRITOS

The Idea



Use a Conditional Generative model, G , to predict the Digital Elevation Model corresponding to a satellite image

The Problem

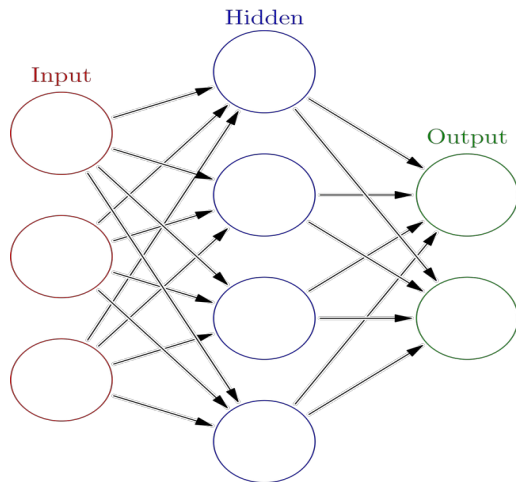
Given a satellite image, x , we want to model the conditional probability of the DEM, Y , namely:

$$P(Y | X = x)$$

Background

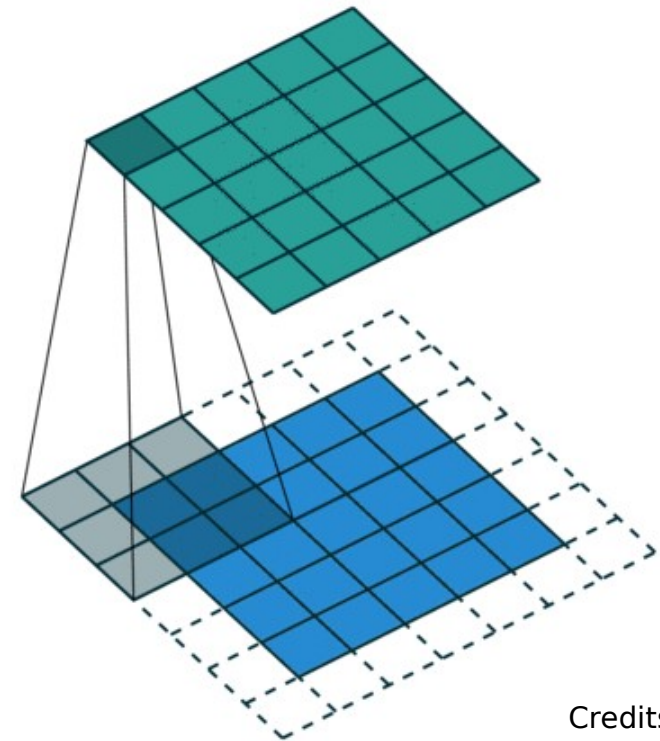
- **Machine Learning**

Algorithms that build a mathematical model based on training data in order to make predictions without being explicitly programmed for the task.



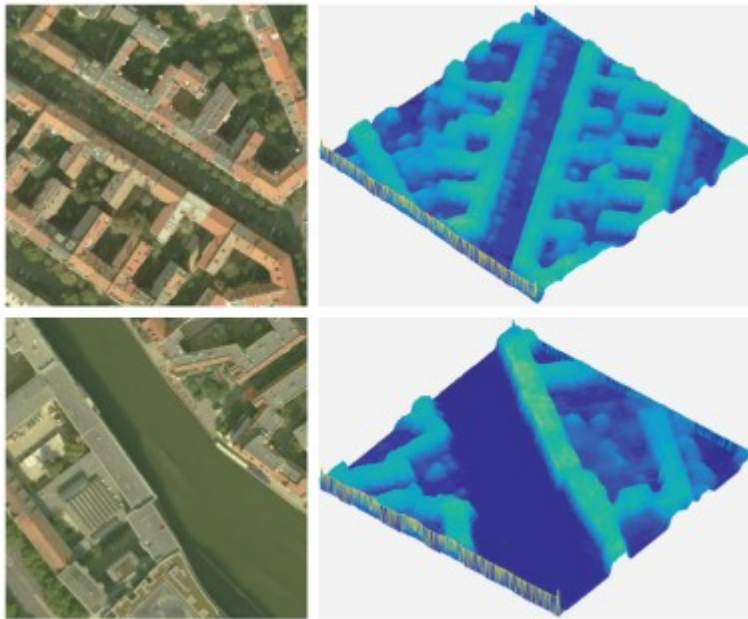
- **Discrete 2D Convolution**

$$[x * h][n_1, n_2] = \sum_{k_1} \sum_{k_2} x[k_1, k_2] h[n_1 - k_1, n_2 - k_2]$$

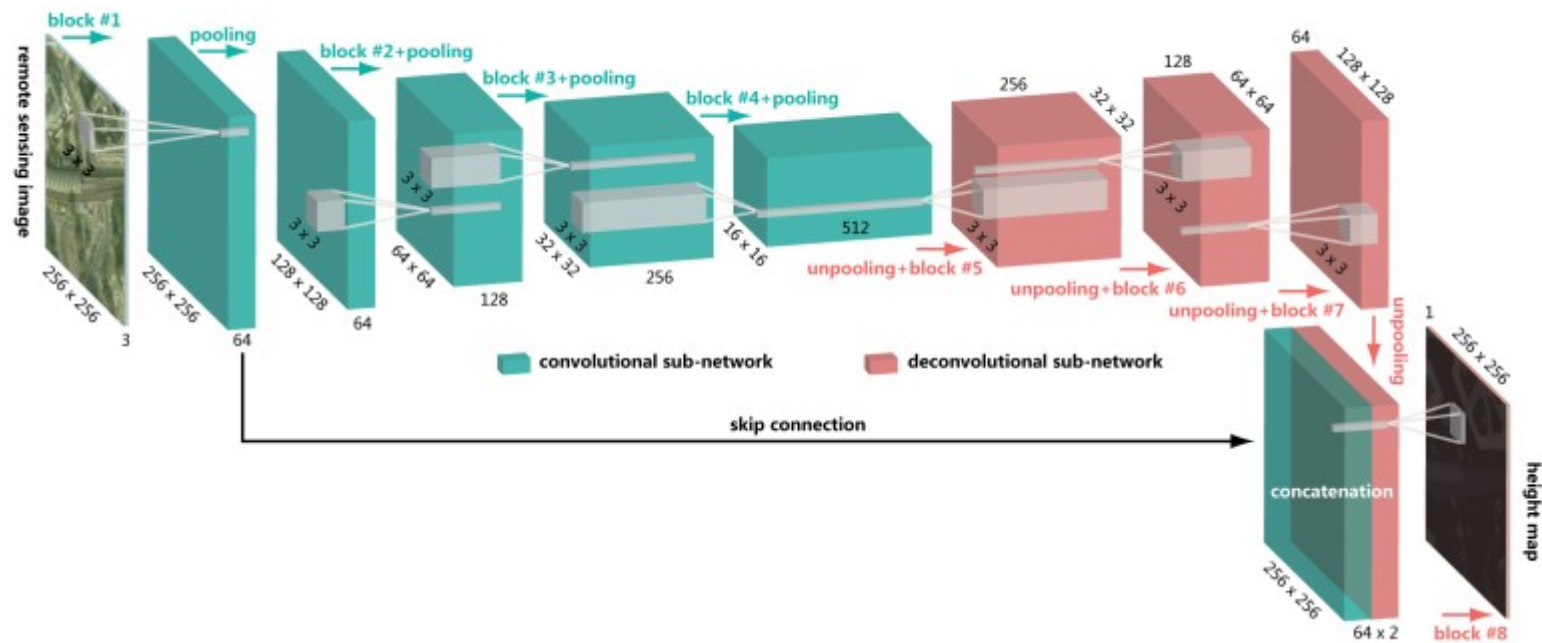


(Mildly) Related Work

IM2HEIGHT: Lichao Mou and Xiao Xiang Zhu



Point cloud visualization of the height estimates for two selected examples.



Final Network Architecture

(Mildly) Related Work

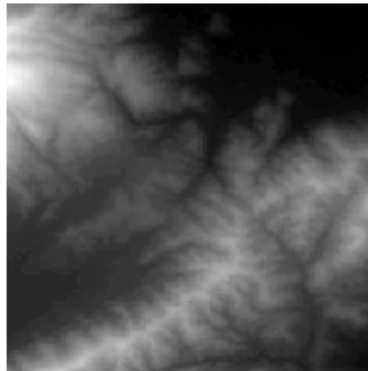
Adjusted IM2HEIGHT architecture for our dataset

Epoch 165

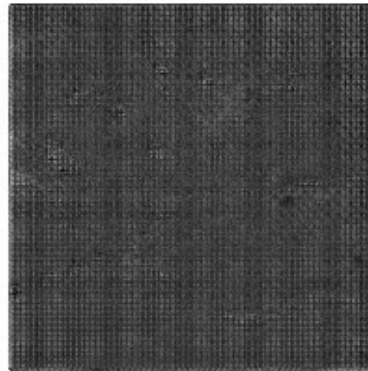
Input Image



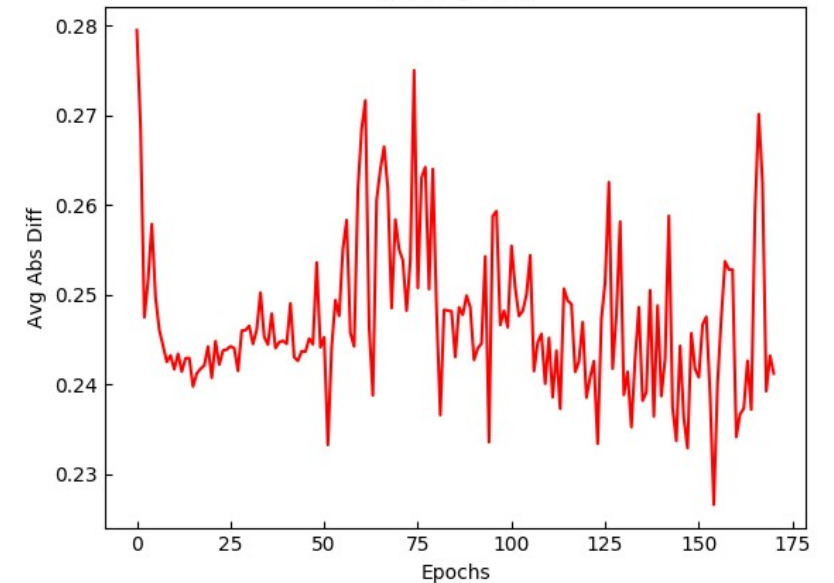
Ground Truth



Predicted Image

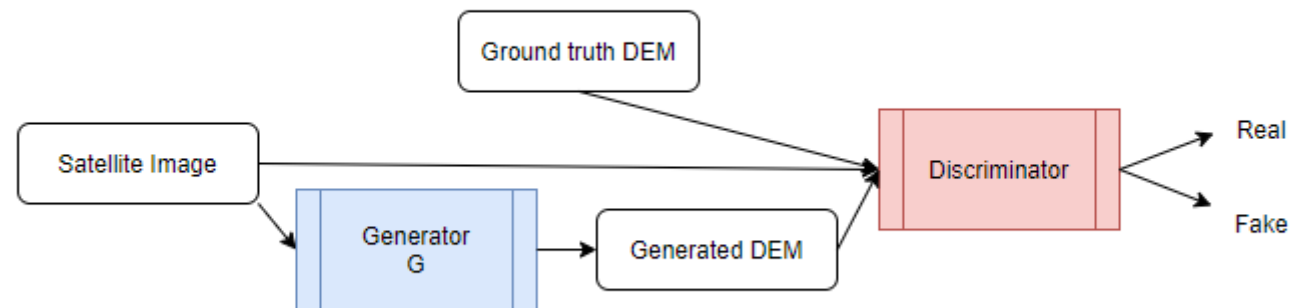


Training error



Our Solution

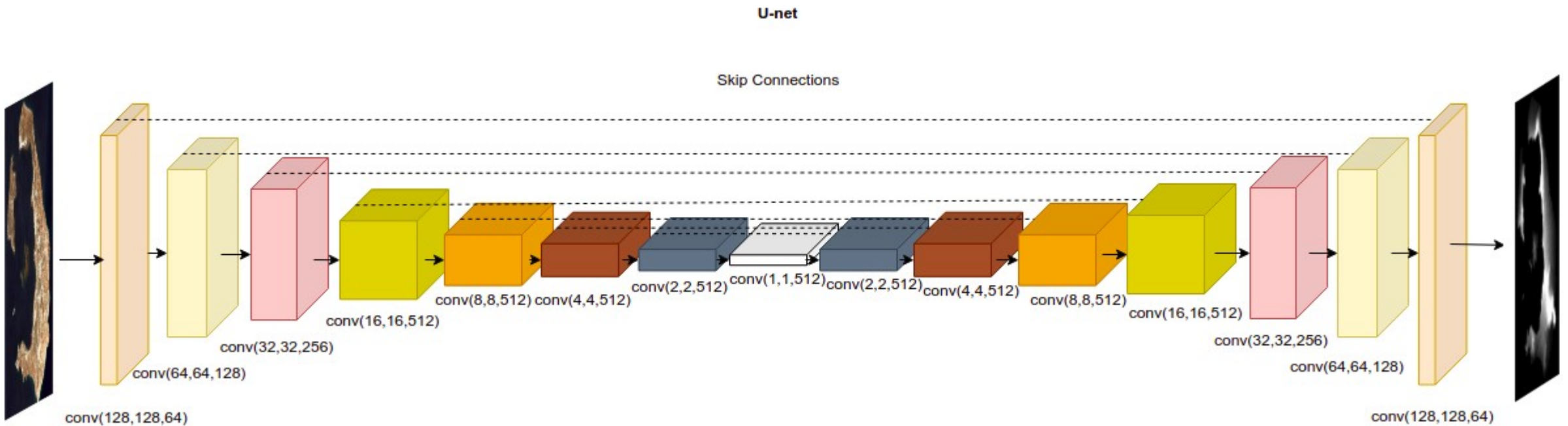
Conditional Generative Adversarial Networks (cGANs)



- Generator: generate DEMs, try to fool the Discriminator
- Discriminator: try to distinguish between real and generated DEMs
- Train them against each other

The Implementation (pix2pix)

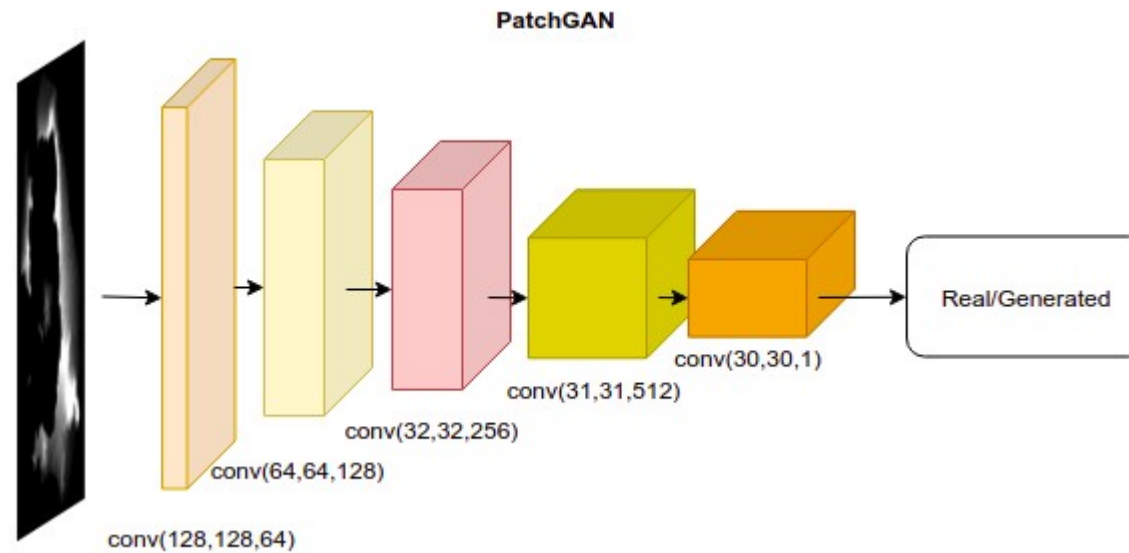
- Generator G



Skip connections preserve global structure (same in satellite image and DEM)

The Implementation (pix2pix)

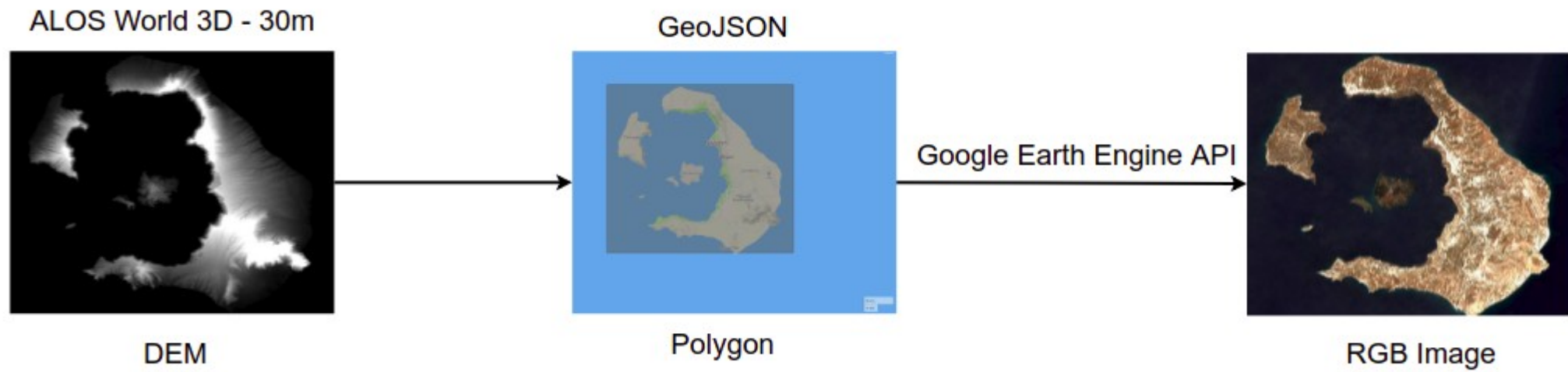
- Discriminator



Assesses DEM's plausibility patch-by-patch

Dataset Construction

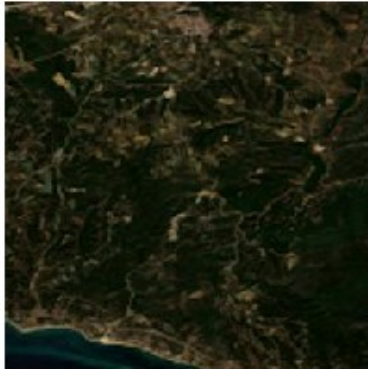
- The satellite image is comprised of the bands [B4, B3, B2] (Copernicus Sentinel-2)
- The difference in resolution is handled by the API



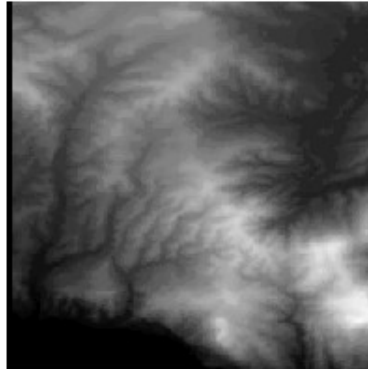
Our Results

Epoch 285

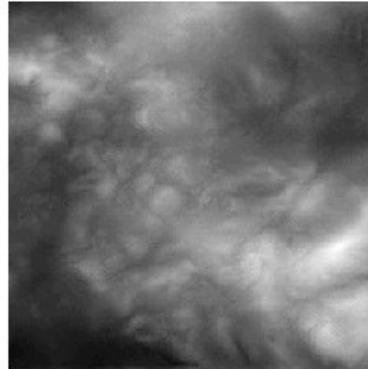
Input Image



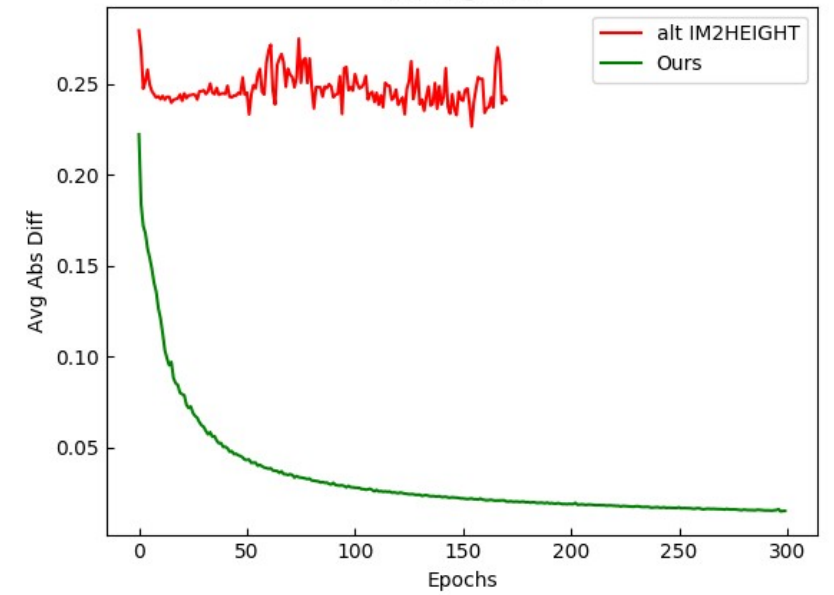
Ground Truth



Predicted Image

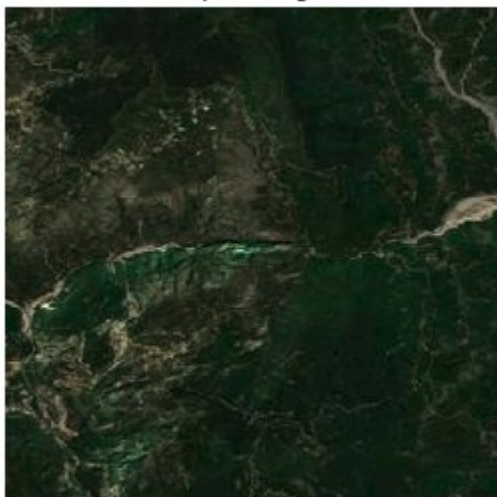


Training error

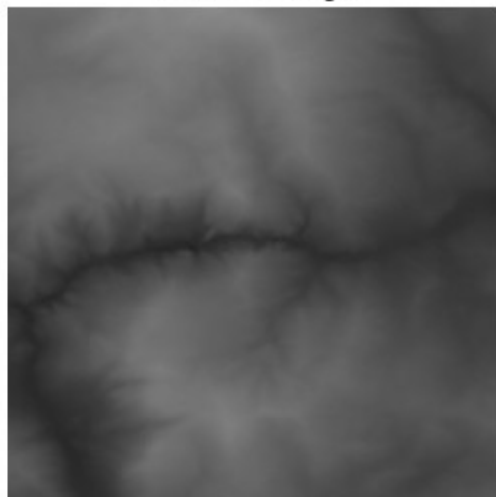


Our Results

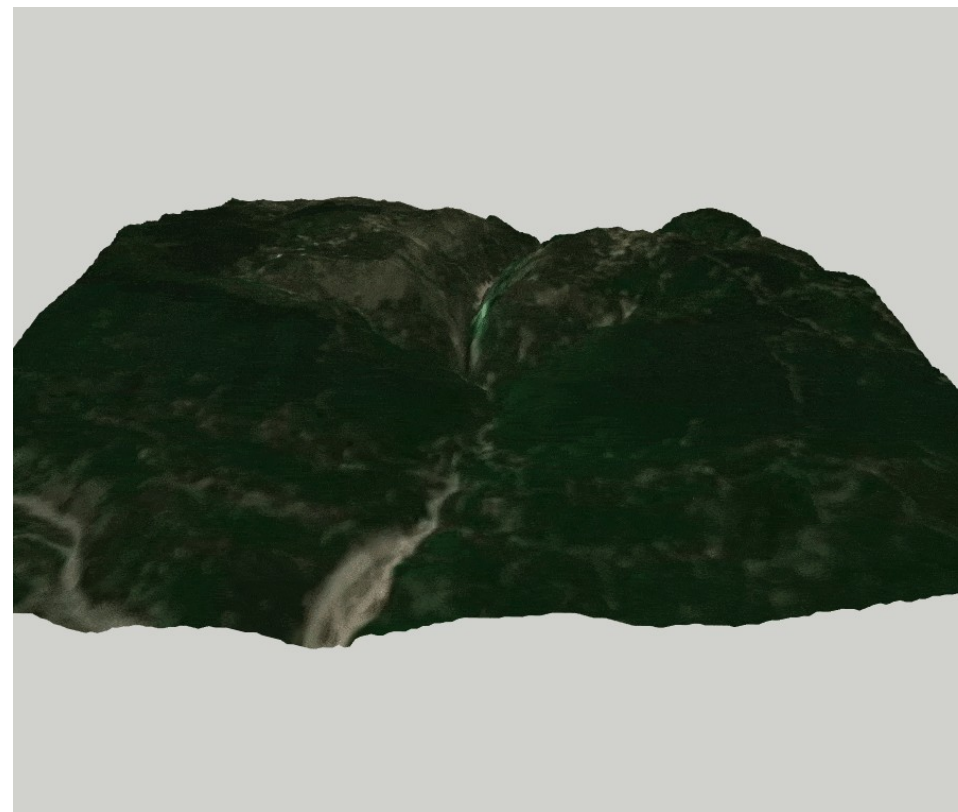
Input Image



Predicted Image

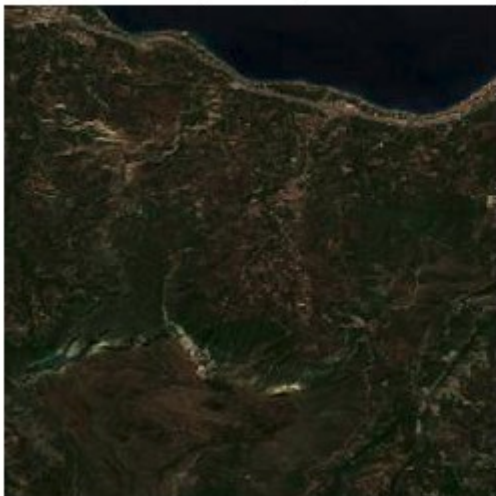


3D
Visualization

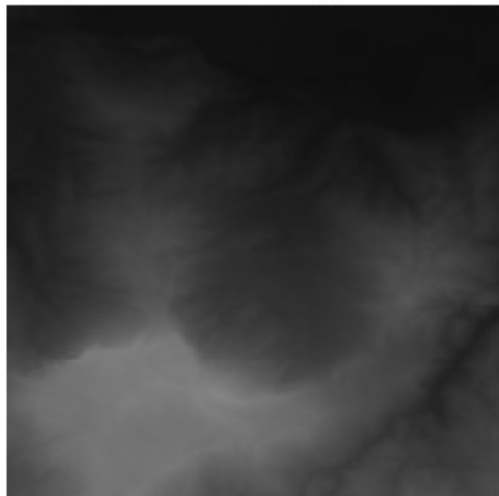


Our Results

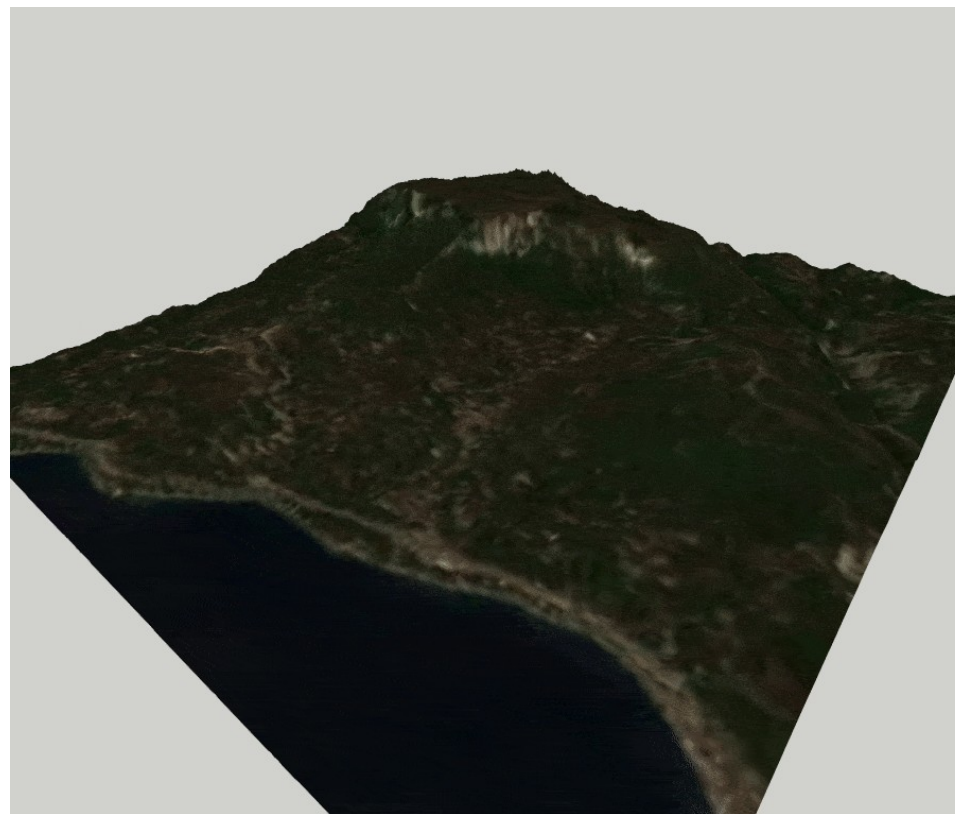
Input Image



Predicted Image



3D
Visualization

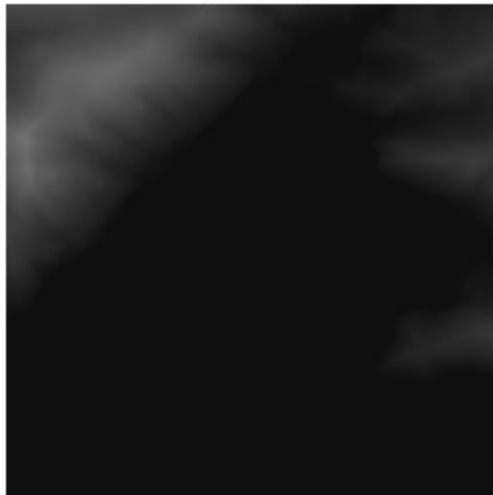


Possible Applications

- On-line Mapping
- Old aerial imagery reconstruction
- Applications in virtual environment rendering

Inverse Problem: Predict Pixel Values based on Elevation

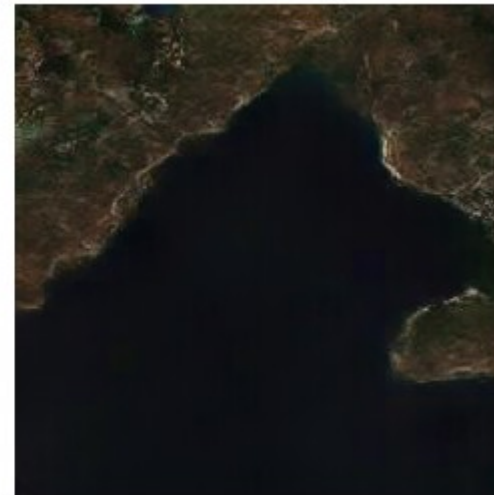
Input Image



Ground Truth



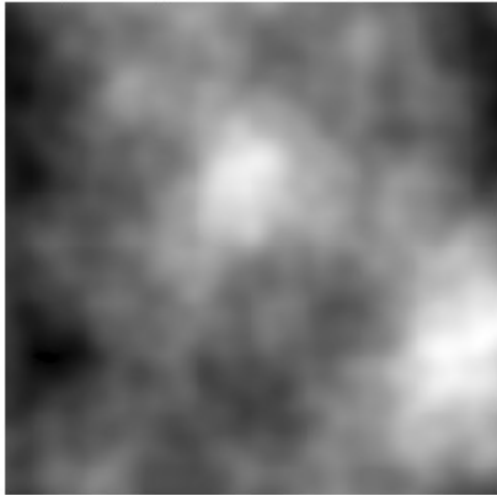
Predicted Image



Possible Applications

Random Terrain Generation using the inverse model

Input Image (Random Perlin Noise)



Predicted Image

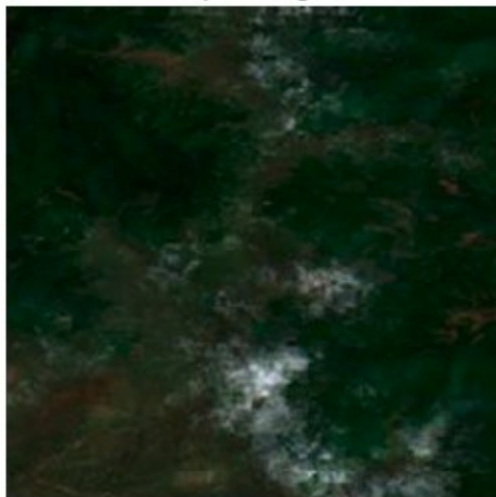


Limitations

- GANs are still an emerging and active area of research
- Predictions on never-before-seen data present a lot of variance
- Predictions of elevation are relative within a satellite image, not absolute.
- Hardware restrictions :(

Difficult Examples

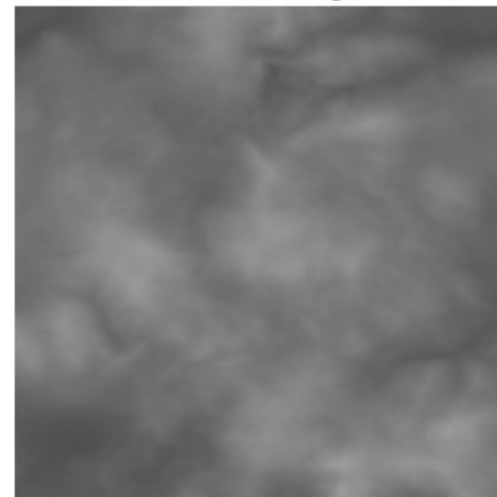
Input Image



Ground Truth

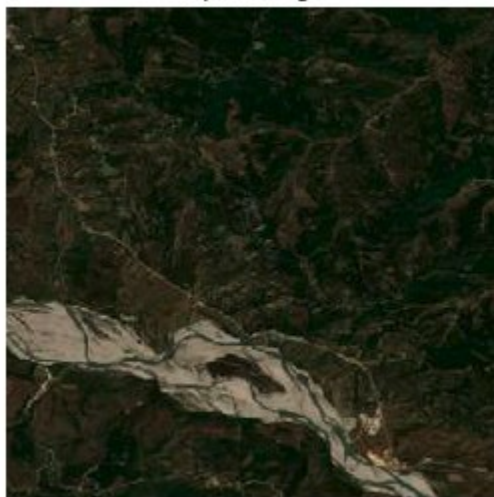


Predicted Image

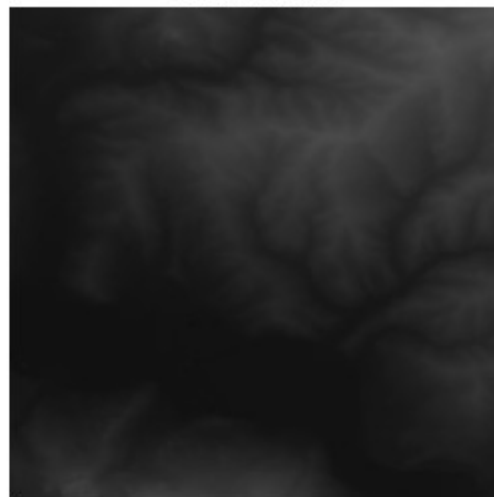


Difficult Examples

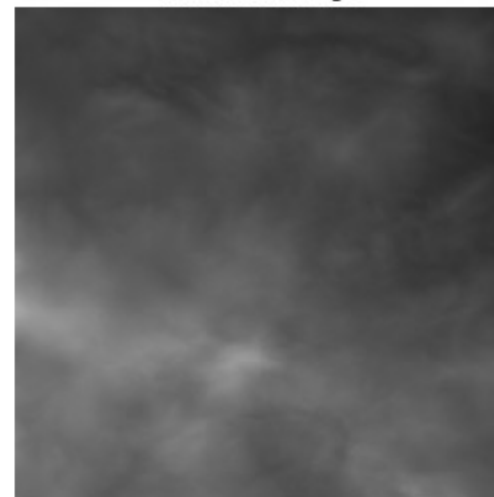
Input Image



Ground Truth

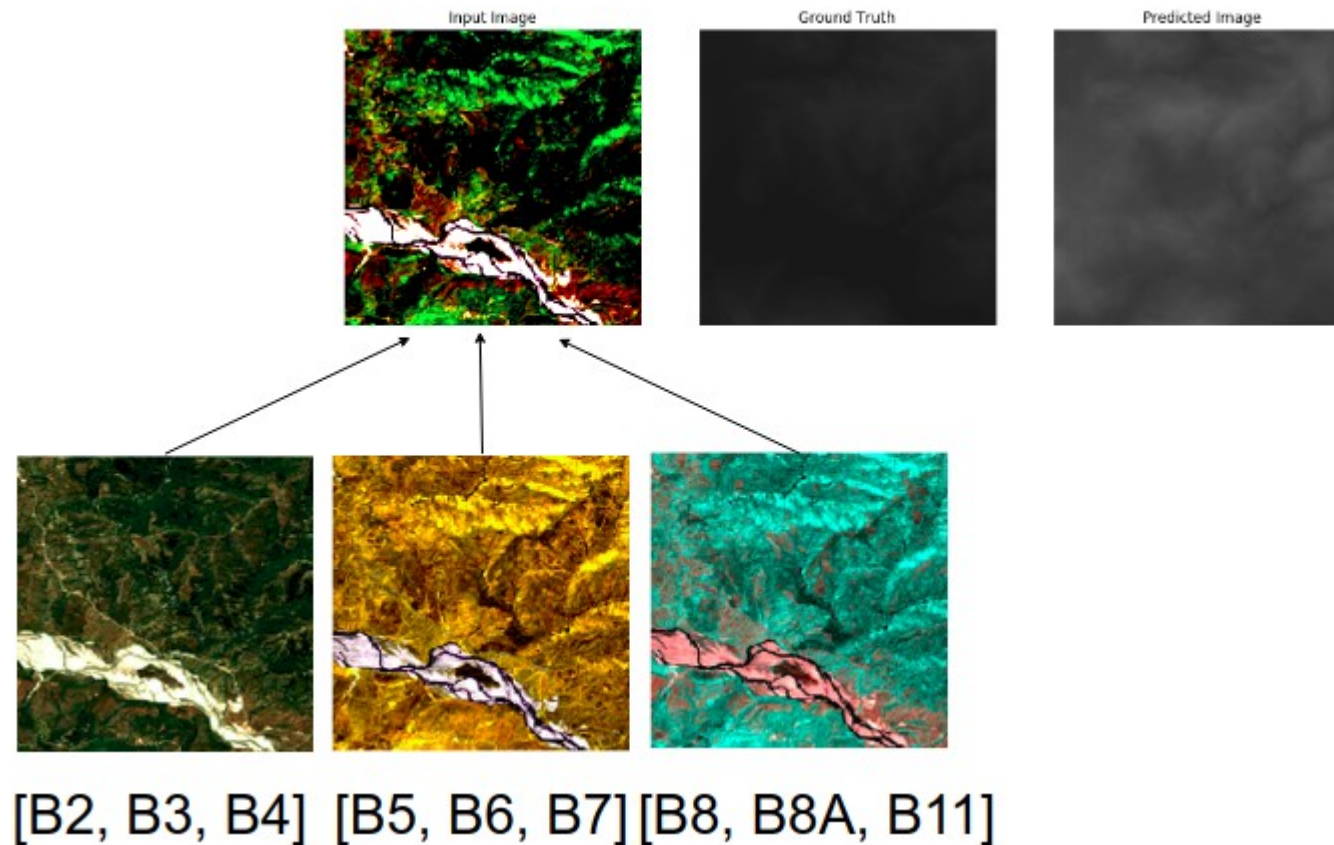


Predicted Image



Solution?

More Data !



Future Work

- The process of synthesizing the data of our dataset itself contains many sources of error (precision, correspondence, lighting, ...)
- We can mitigate their effects by working directly with the exact data captured by satellites, drones, ...
- Depth Maps

References

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